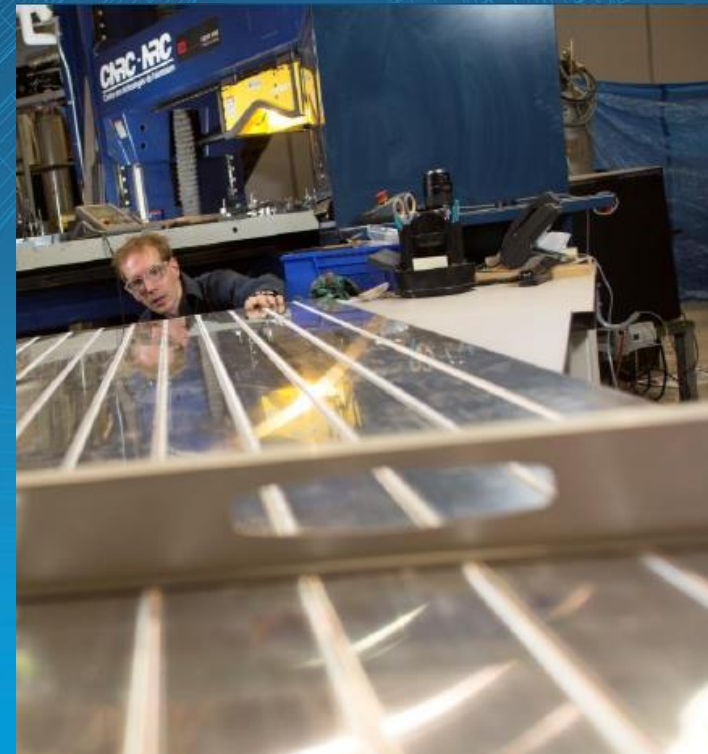


# Developments in friction stir & spot welding: tailored blanks & Al/Steel joining techniques

Global Automotive Lightweight Materials  
2015

François Nadeau ing., M.Sc.  
NRC-Saguenay  
April 14<sup>th</sup> 2015



Conseil national  
de recherches Canada

National Research  
Council Canada

Canada

# Who's NRC ?



## NRC:

- 4000 employees accross Canada

## NRC (Saguenay):

- 35 employees



NRC-Saguenay (Aluminium Technology Centre)

## Shaping

Extrusion

Hot/warm/cold forming

Hydroforming

Semi-solid casting (SEED)

## Joining

Structural adhesives

Welding processes

Surface treatment

Environmental durability

Hybrid joining

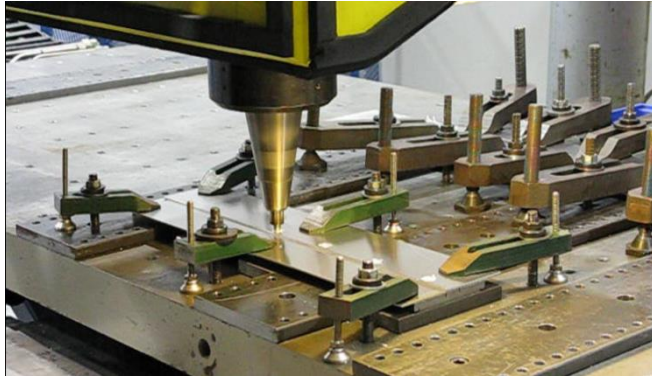
GMAW/GTAW

Laser & HLAW welding

Friction stir welding

## Corrosion

# Outline



Tailor welded blanks: FSW & laser comparison



Gantry FSW systems



Robotic FSW/FSSW systems

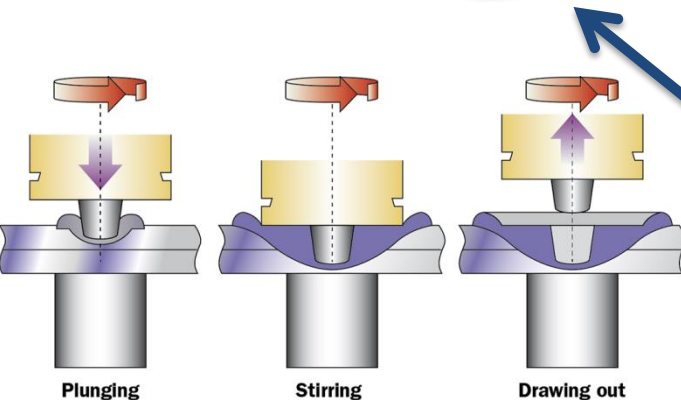
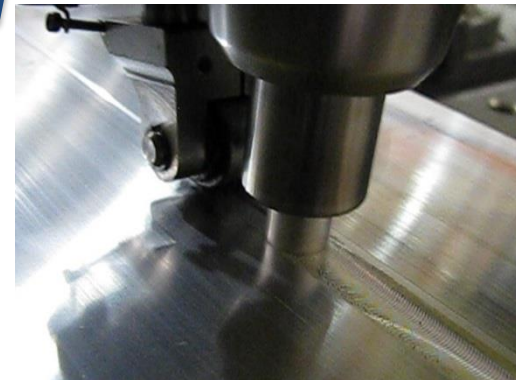
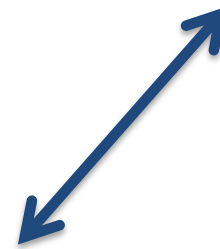


FSW AI/Steel: techniques & joint performance

FSSW: techniques & joint performance

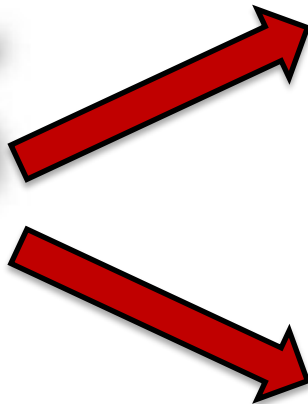


Hybrid joining: welding processes + adhesives

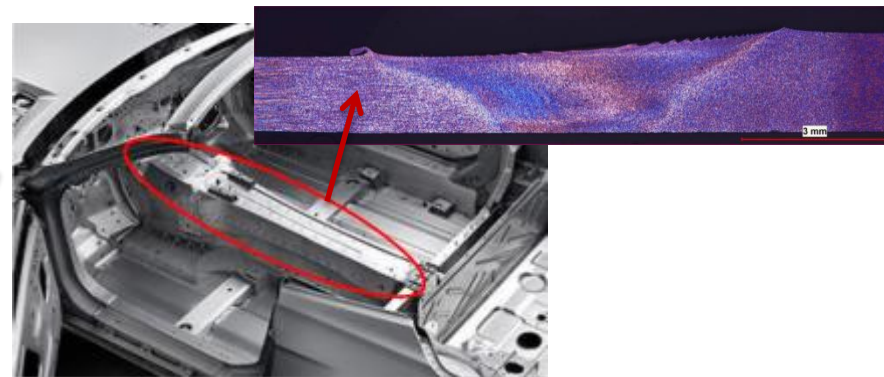


# Tailor welded blanks: FSW & laser comparison

- Interesting lightweighting possibility (body-in-white & structural parts)
- Goal: Increase productivity without decreasing formability

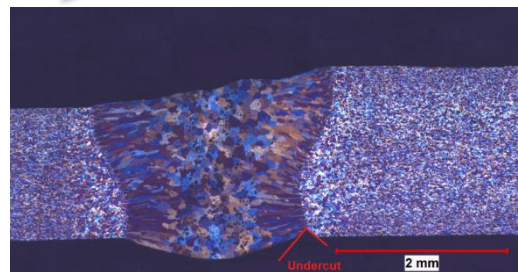


## Friction stir welding



Mercedes SL

## Autogenous laser welding



- High productivity
- Hard to control geometrical defects
- Hot cracking sensitivity

Thickness ratio	Approximate weight savings (part)
1.5 : 1	≈ 15 %
2 : 1	≈ 30 %

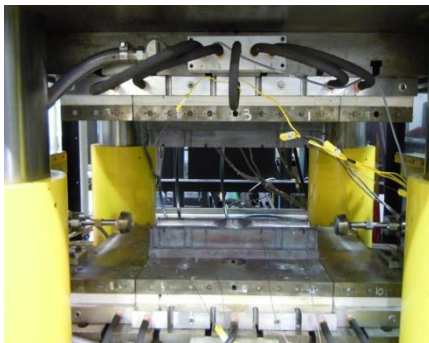
# Tailor welded blanks: FSW & laser comparison

**Cold forming**

Room temperature

**Warm forming**

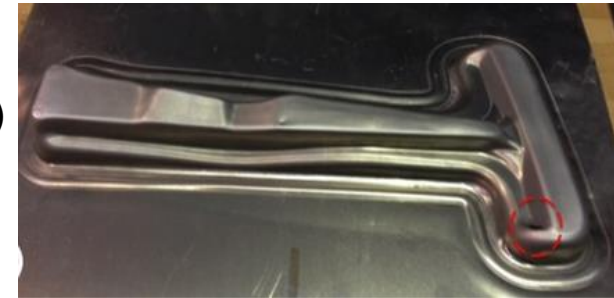
200°C @ 350°C



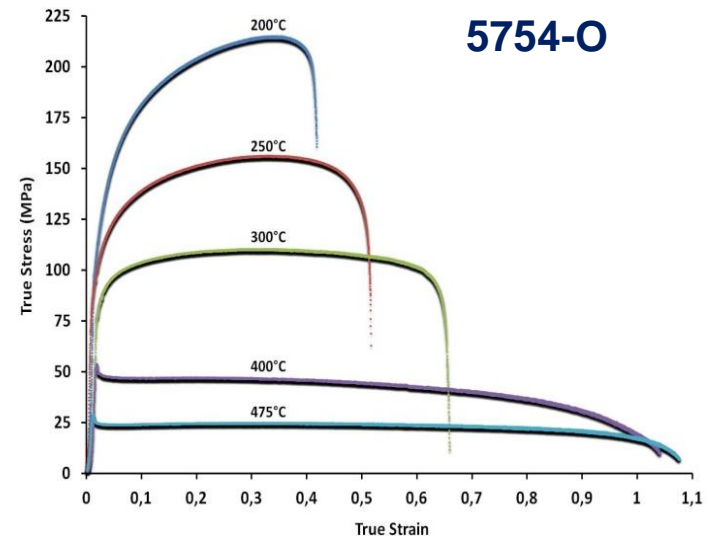
**Hot stamping**

400°C @ 530°C

5052-O  
5754-O  
5182-O (+ Mn)  
6016-T4  
6111-T4  
7075-T6



5754-O



7075-T6

- Solution heat treatment
- Quench
- Artificial aging

# Tailor welded blanks: FSW & laser comparison



Good weldability at high travel speed: at least 3.0 m/min

Pin tool ( $\Phi$  8.5 mm)

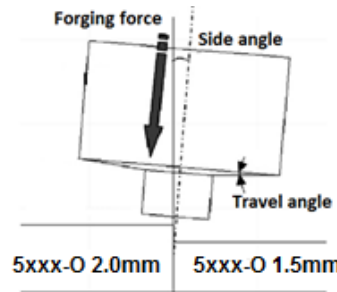
2000 RPM, 1.0 m/min, 5.5 kN



2000 RPM, 2.3 m/min, 6.25 kN

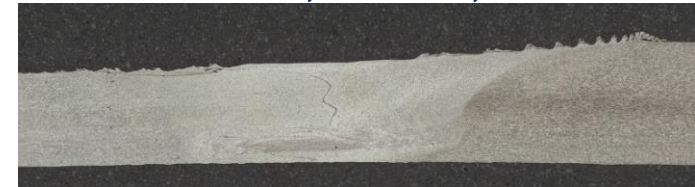


2000 RPM, 3.0 m/min, 6.8 kN



Pin tool ( $\Phi$  12.0 mm)

2000 RPM, 1.0 m/min, 6.0 kN



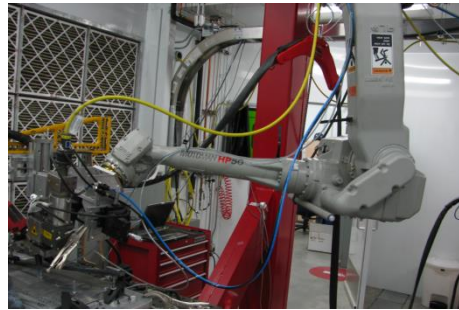
2000 RPM, 2.3 m/min, 10.0 kN



2000 RPM, 3.0 m/min, 11.5 kN



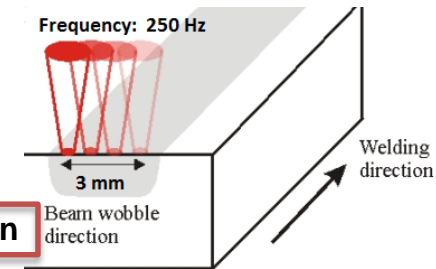
# Tailor welded blanks: FSW & laser comparison



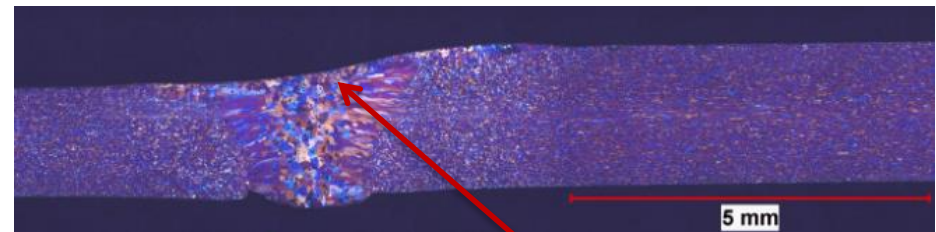
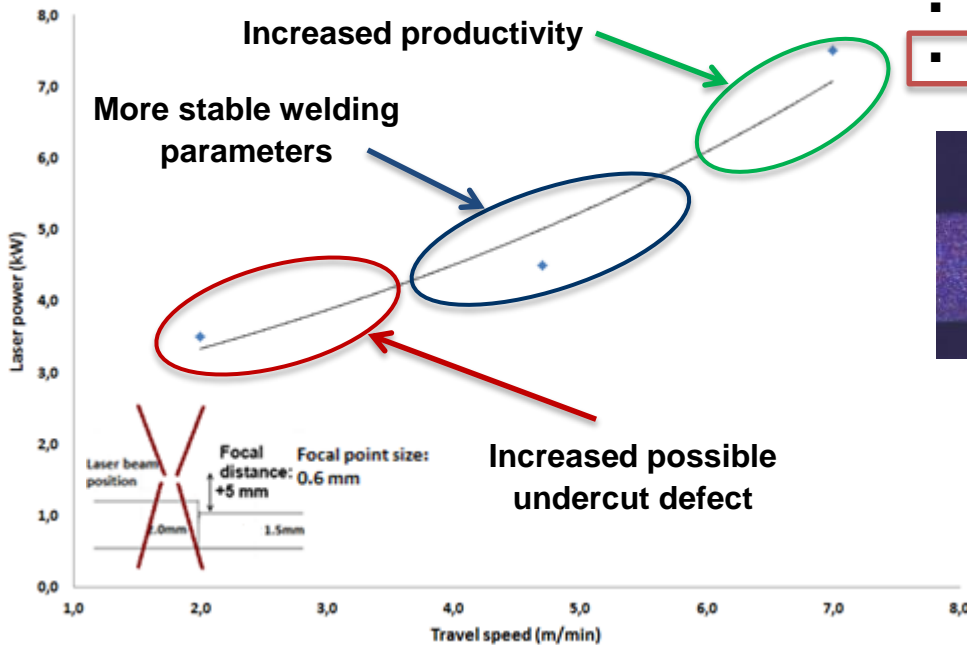
Robot (single pass)



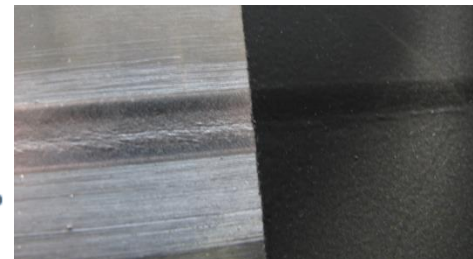
'Remote on the fly' (double-pass)



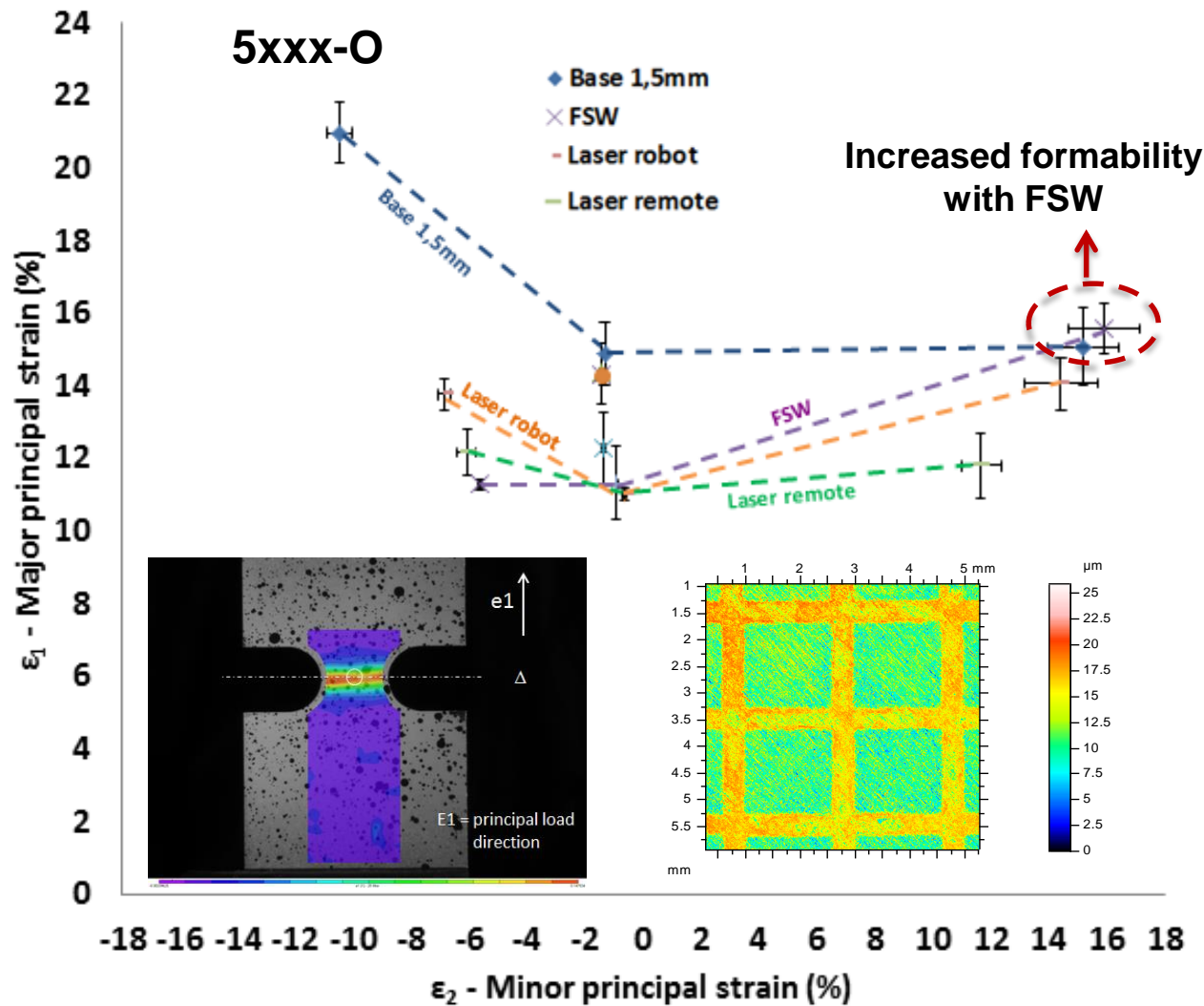
- First pass: 7.5 kW, 7.0 m/min
- Second pass: 4.0 kW, 2.0 m/min



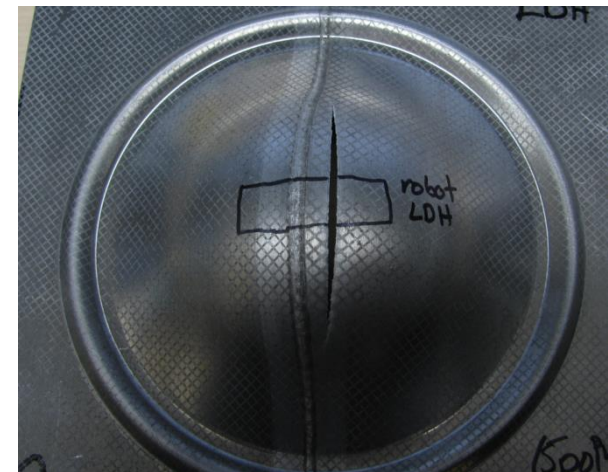
Smoother surface finish  
Limitation of undercuts



# Tailor welded blanks: FSW & laser comparison



**FSW**



**Laser robot**



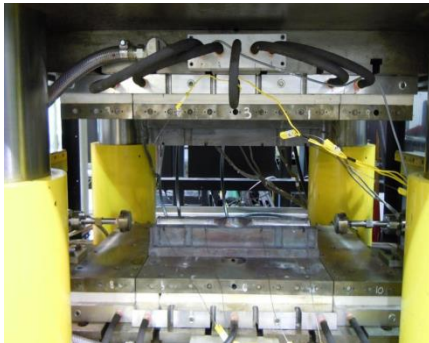
# Tailor welded blanks: FSW & laser comparison

**Cold forming**

Room temperature

**Warm forming**

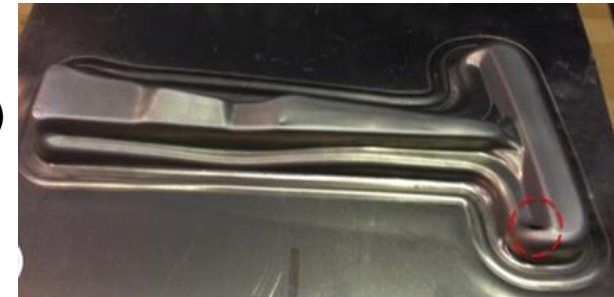
200°C @ 350°C



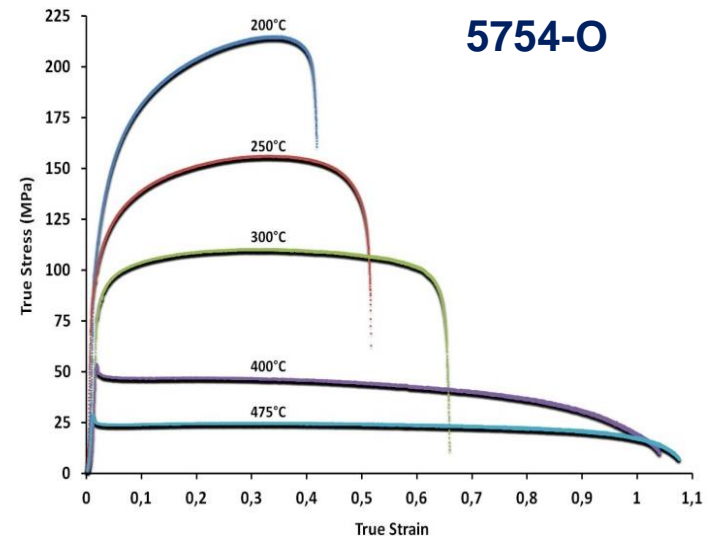
**Hot stamping**

400°C @ 530°C

5052-O  
5754-O  
5182-O (+ Mn)  
6016-T4  
6111-T4  
7075-T6



5754-O



7075-T6

- Solution heat treatment
- Quench
- Artificial aging

# Tailor welded blanks: FSW & laser comparison

Hot forming issues with FSW of tailor welded blanks...



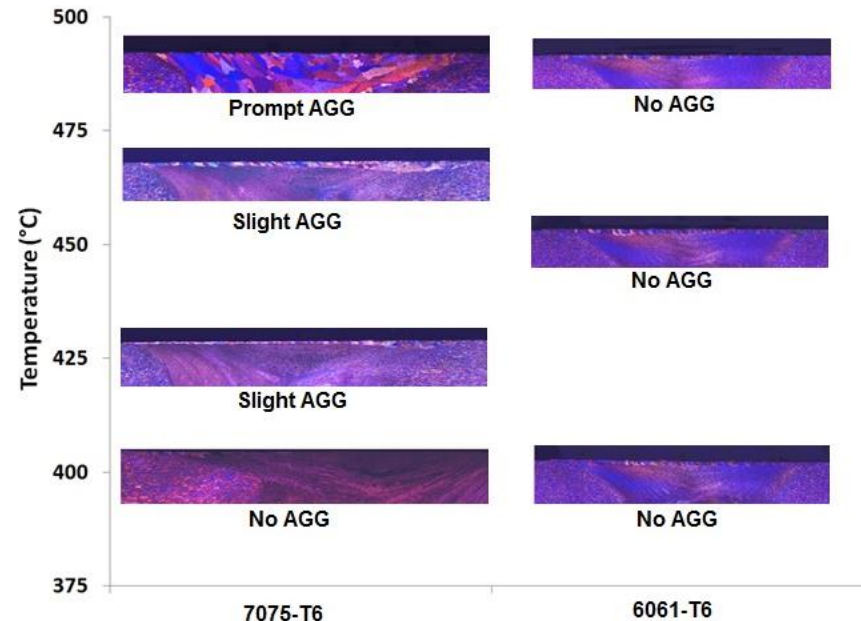
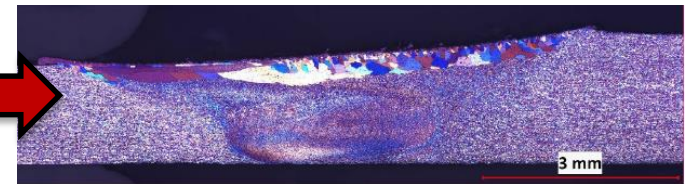
Aluminum  
B-pillar



5083 SPF part, 1.5 / 2.0 mm



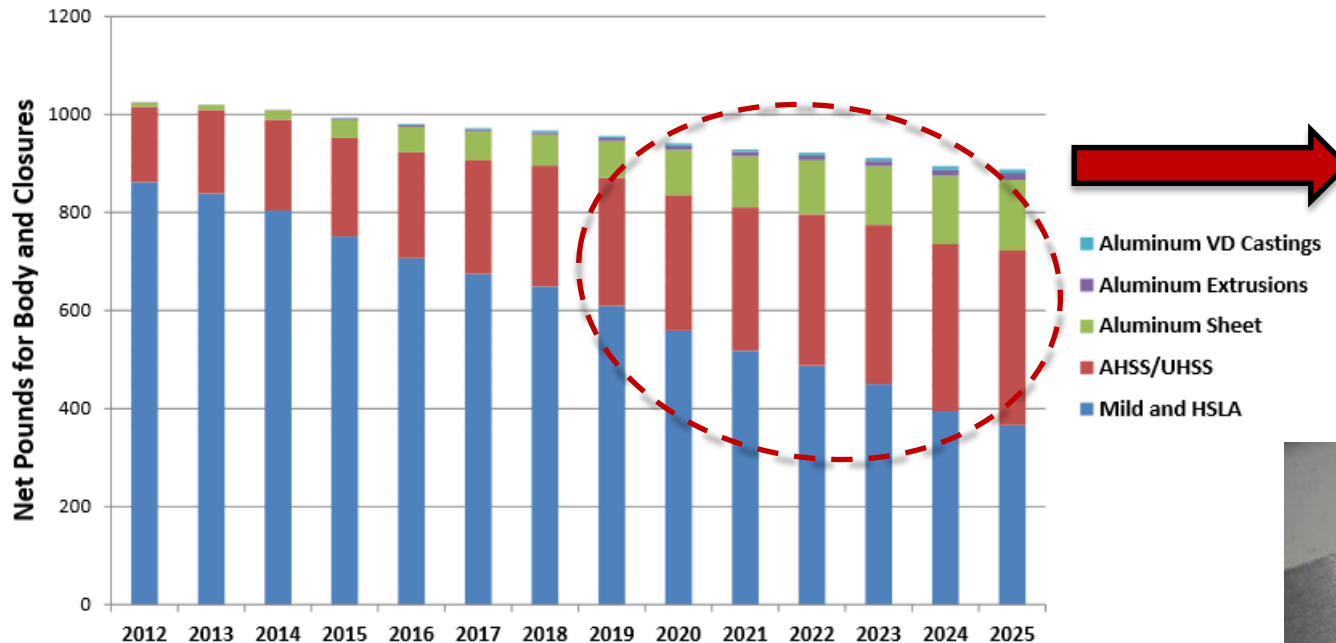
Abnormal grain growth (AGG)



- High travel speed:
  - Lower heat input (thin sheet):
- ↑ AGG

# FSW of Al/Steel: techniques & joint performance

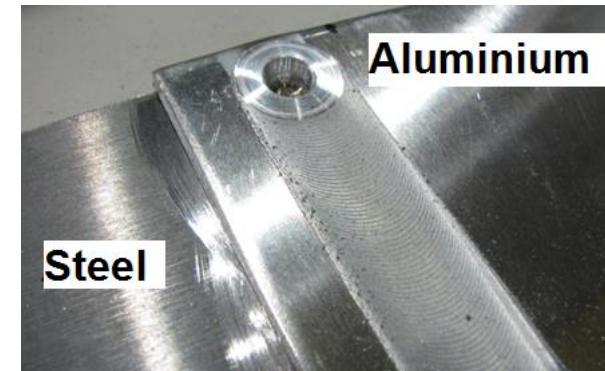
- Automotive trend toward dissimilar material joining (average body & closures)



Ducker worldwide (2015)

Constant growth of...

- Aluminum
- AHSS/UHSS



- Current fusion welding processes need improvement
  - Metallurgical incompatibility (fragile intermetallics)
- Solid-state joining processes (FSW) are attractive in this regard

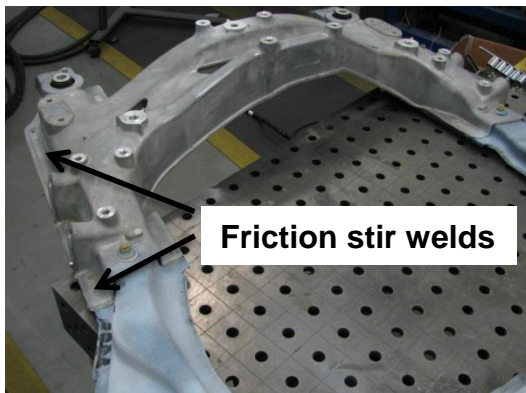
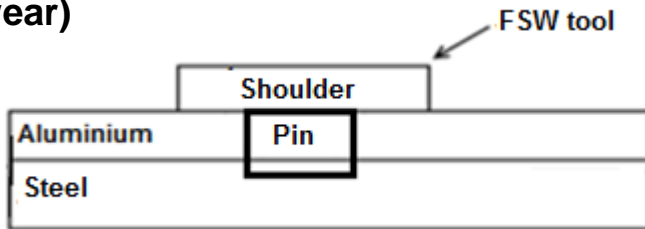
# FSW of Al/Steel: techniques & joint performance

## Friction stir welding (Al / Steel)

Conventional



- FSW pin tool enters slightly into substrate
- Wear-resistant tool material (potential wear)

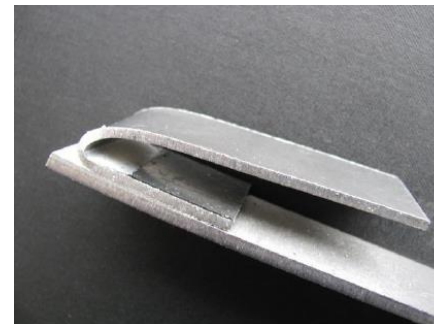


Honda

Assisted FSW (NRC)



- FSW pin tool do not enter into substrate
- Typical tool materials for Al / Al FSW



- Passed 90° bend

# FSW of Al/Steel: techniques & joint performance

## ■ Conventional FSW (Al / Steel)

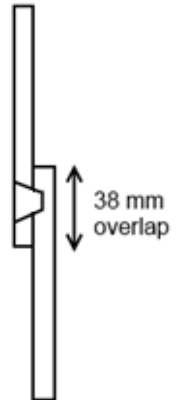
### ➤ Joint performance

Aluminum sheet thickness	Shoulder & pin diameters	Forge force	Joint resistance Load / weld length <sup>1</sup>
mm	mm	kN	N / mm
≈ 1.0 - 2.0	11.0 / 4.0	9.75	316.5 +/- 14.1
≈ 3.0	14.0 / 5.0	12.00	431.2 +/- 51.8

<sup>1</sup>Joint failure at interface

Aluminum alloy	Tensile strength	Maximum thickness for failure in base material (11mm shoulder tool)
	MPa	mm
6016-T4	220	1.44
5754-O	230	1.38
5182-O	275	1.15
6070-T4	320	0.99
7075-T6	550	<b>0.58</b>

Single lap-shear test

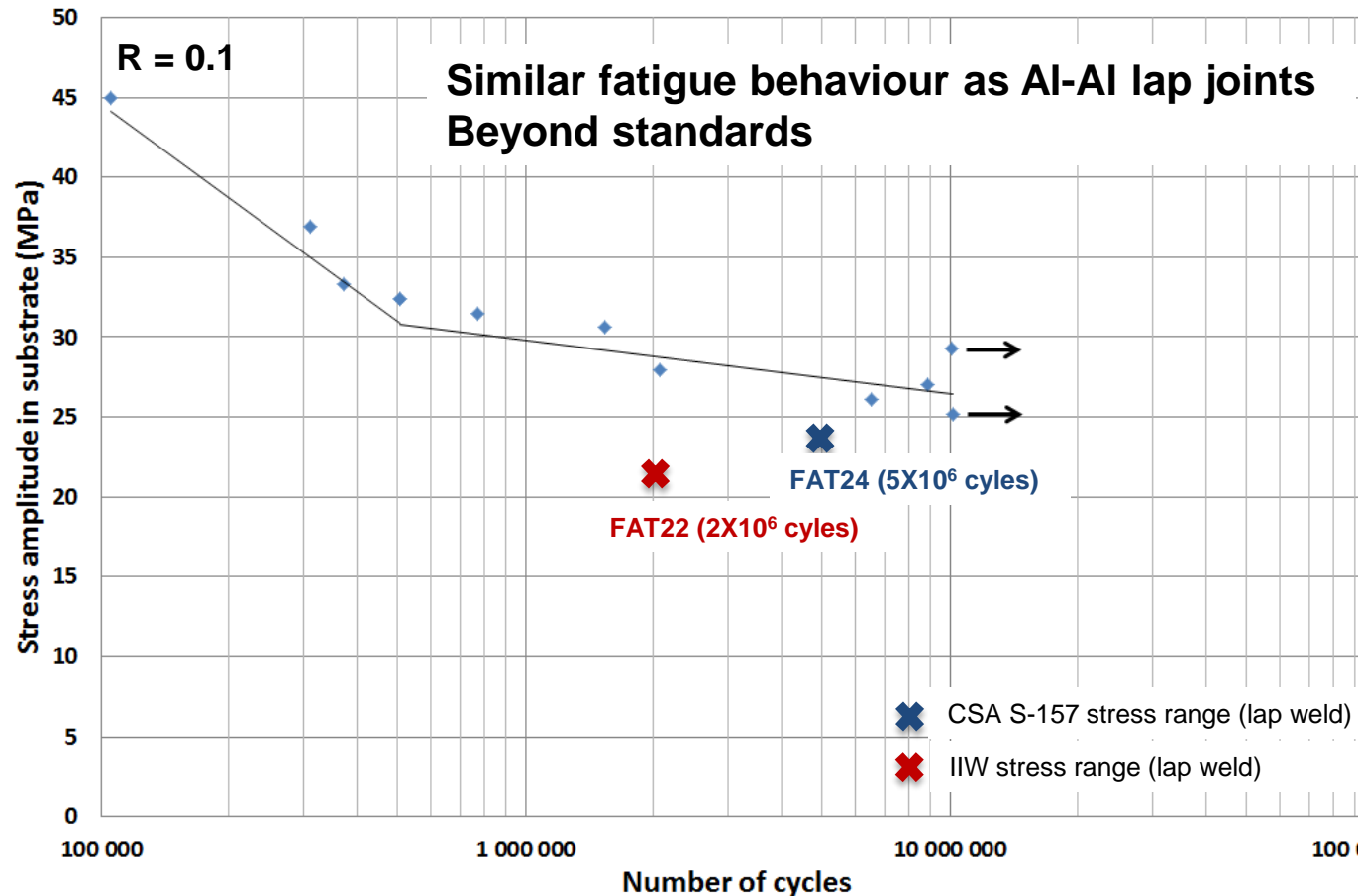


Increased interface length yields higher joint resistance  
(≈ 80% joint efficiency vs FSW Al/Al)

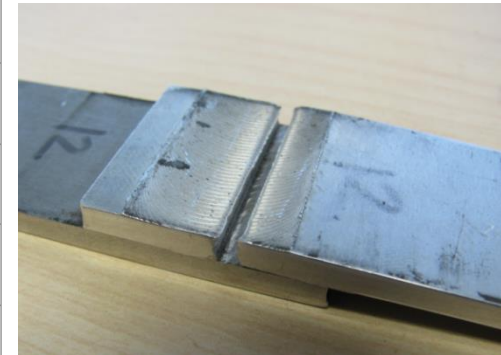
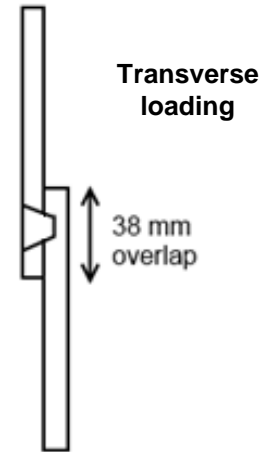
# FSW of Al/Steel: techniques & joint performance

## Conventional FSW (Al / Steel)

### ➤ Joint performance (fatigue)



Single lap-shear test



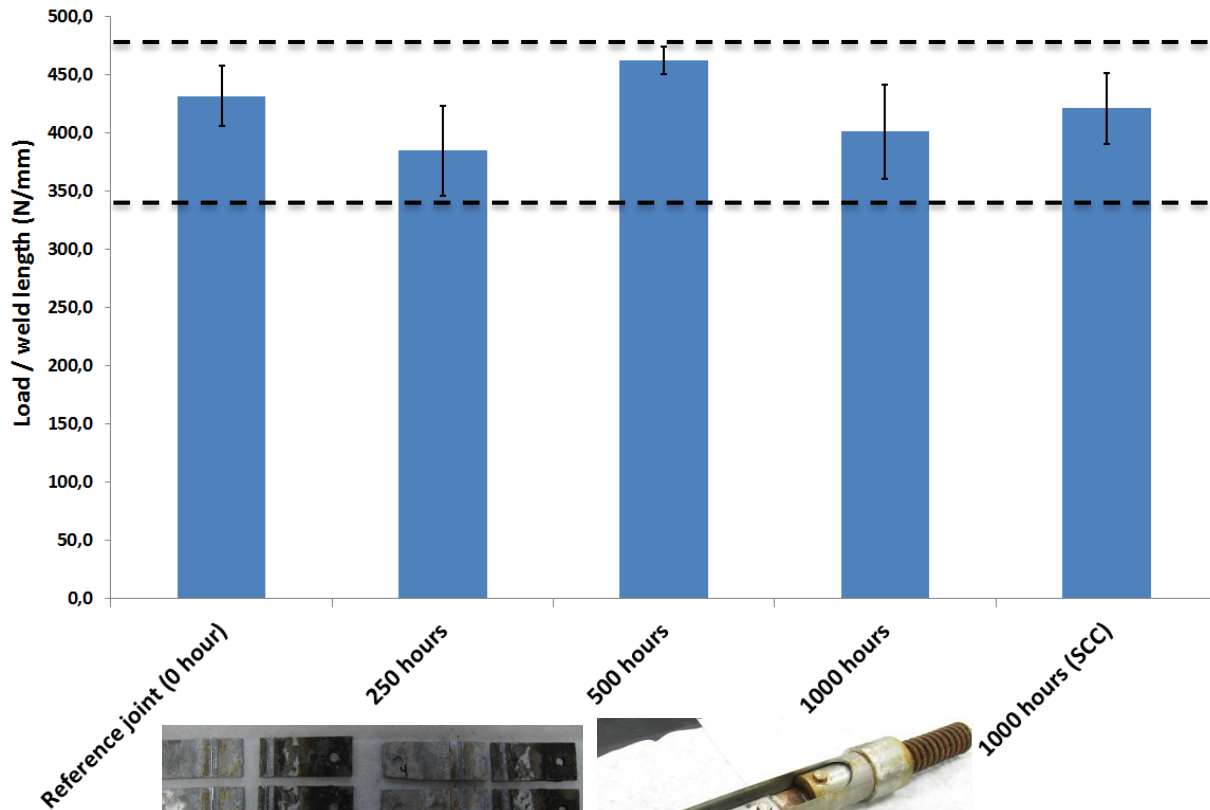
### Rupture through:

- Al top sheet
- Retreating side

# FSW of Al/Steel: techniques & joint performance

## ■ Conventional FSW (Al / Steel)

### ➤ Environmental durability performance

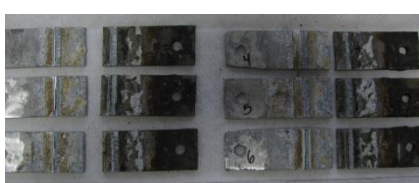


Static mechanical properties not clearly affected in durability testing



### GM9505P Cycle G (30 cycles)

- 2 hours @ -30°C
- 2 hours @ room temperature
- 2 hours @ 70°C
- 2 hours in environmental chamber
  - 2 hours in salt spray
  - 16 hours in high humidity



\*SCC load: 22% of single lap shear strength

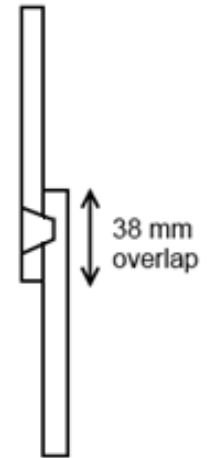
# FSW of Al/Steel: techniques & joint performance

## Assisted FSW - NRC (Al / Steel)

### ➤ Joint performance

Tierce material	Shoulder diameter	Forge force	Joint resistance Load / weld length
	mm	kN	N / mm
Conventionnal FSW	11.0	9.75	316.5 +/- 14.1 <sup>1</sup>
Lower-strength method	11.0	5.00	234.8 +/- 5.6 <sup>1</sup>
	18.0	13.50	338.0 +/- 7.6 <sup>1</sup>
Higher-strength method	11.0	5.00	408.8 +/- 0.7 <sup>2</sup>

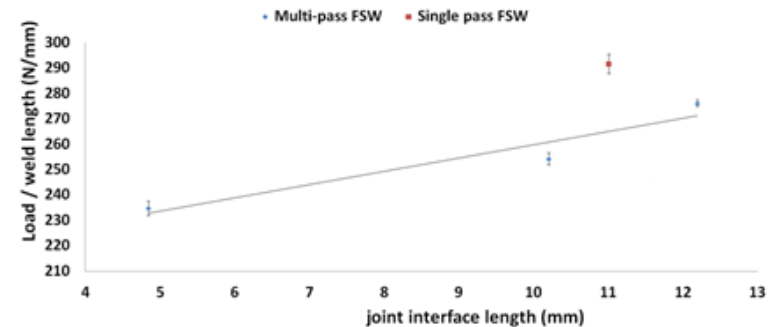
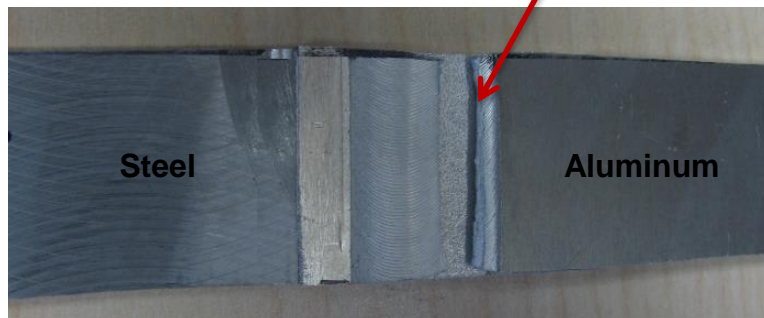
Single lap-shear test



<sup>1</sup>Joint failure at interface

<sup>2</sup>Joint failure in base material (2.0mm thick)

Failure in base material





# Hybrid joining: welding processes / structural adhesives

Pre-welding application  
of adhesive

Post-welding application  
of adhesive

Al

+

Al

OR

Al

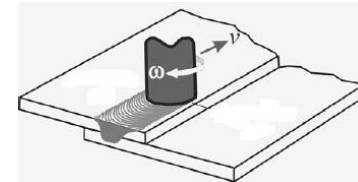
+

Steel

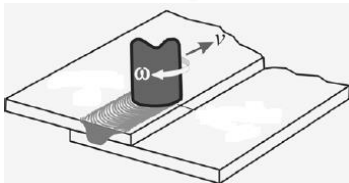
Step 1



Step 1



Step 2



Step 2

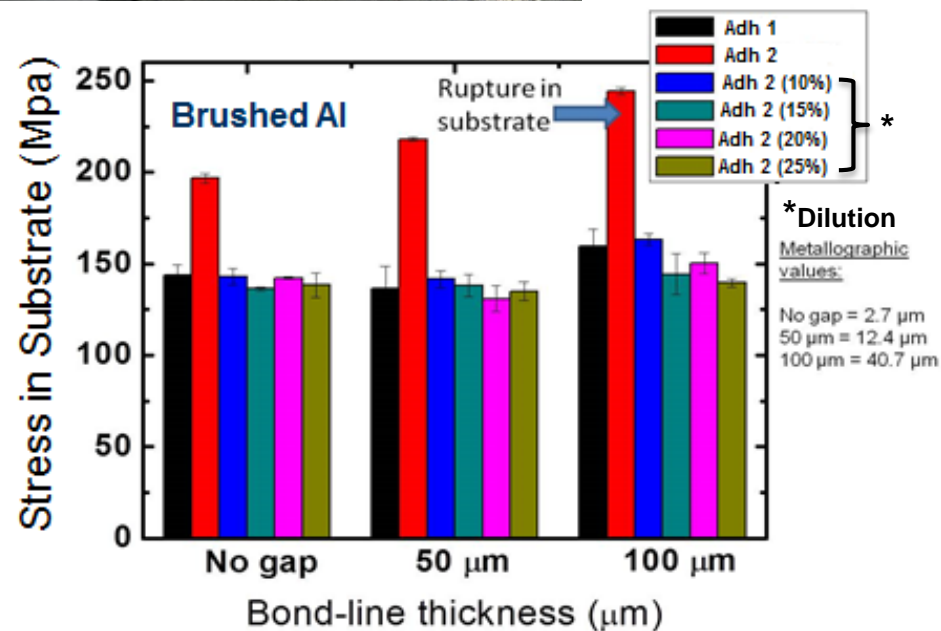
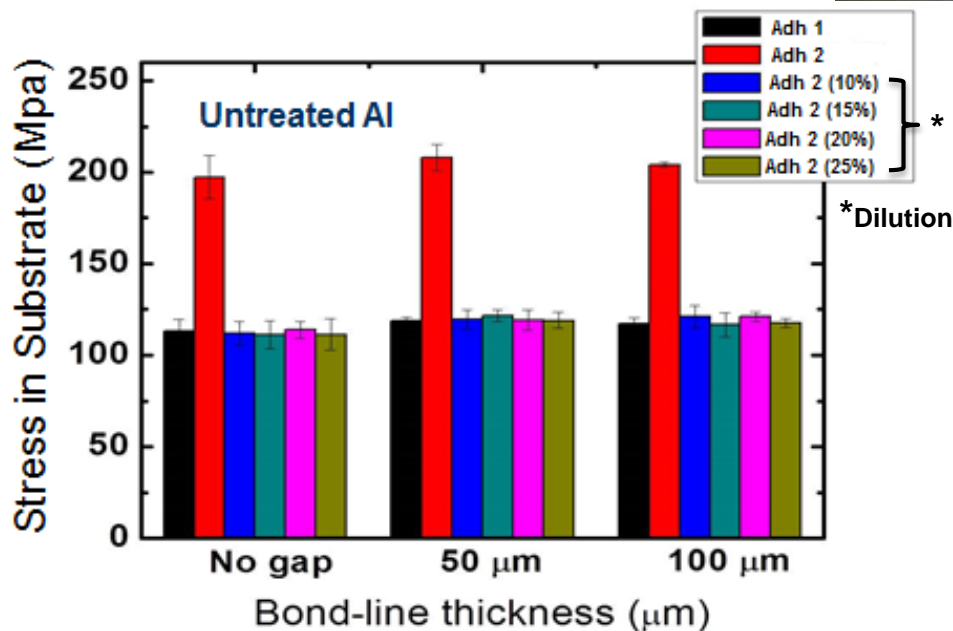
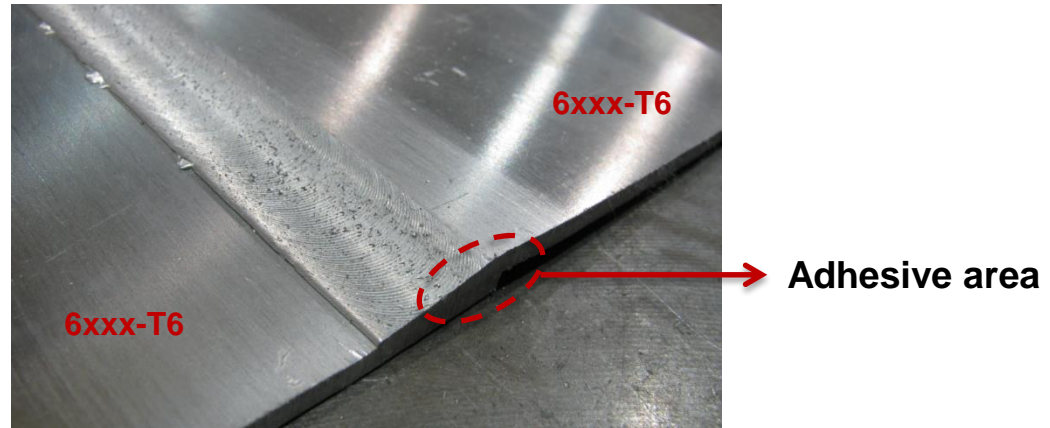


# Hybrid joining: welding processes / structural adhesives

## AI / AI hybrid joining ➤ FSW

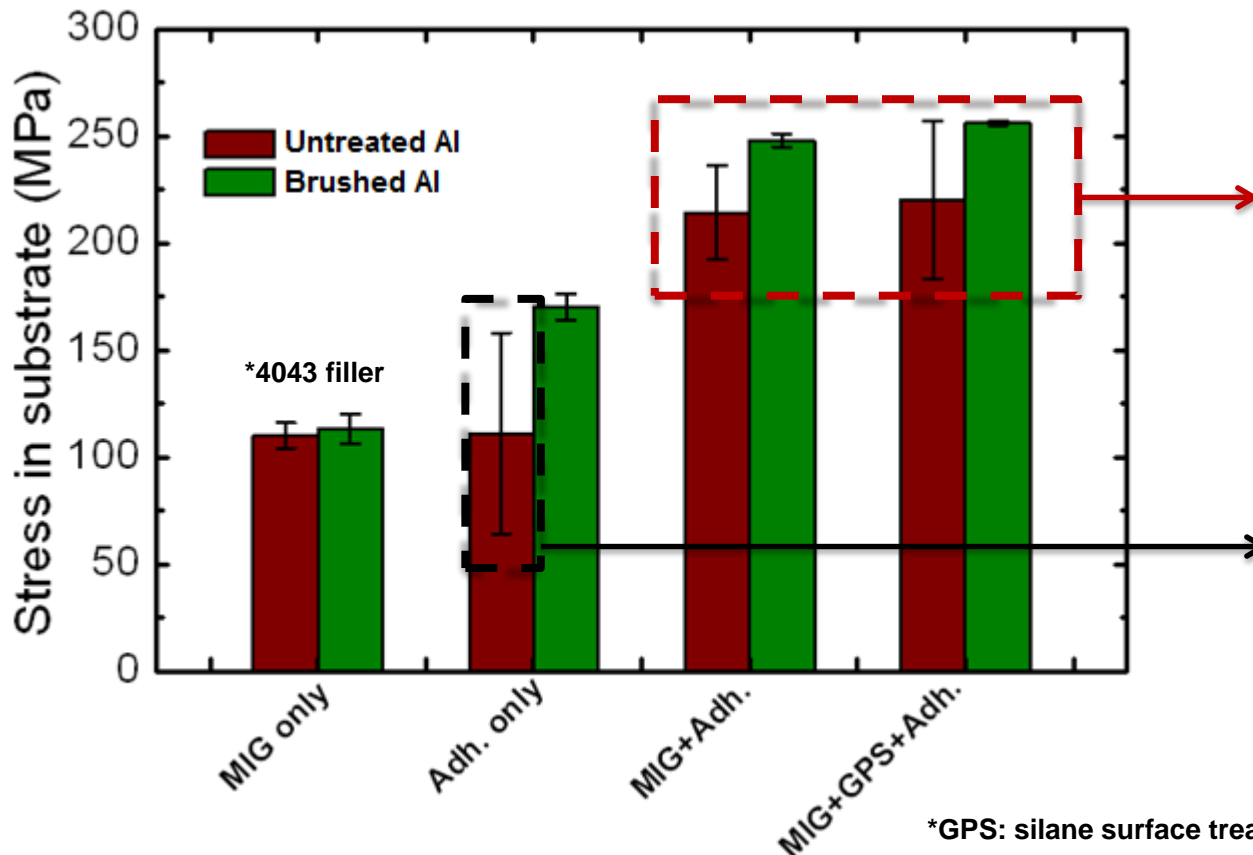
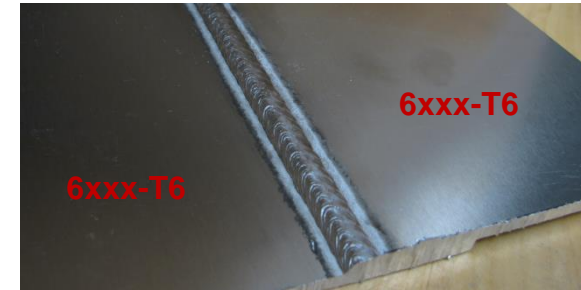
+ 65% joint strength in hybrid joining (untreated AI) vs FSW

Up to + 105% joint strength in hybrid joining (brushed AI) vs FSW



# Hybrid joining: welding processes / structural adhesives

- **Al / Al hybrid joining**
  - **GMAW (MIG)**



**+ 50% joint strength in hybrid joining vs GMAW or adhesive**

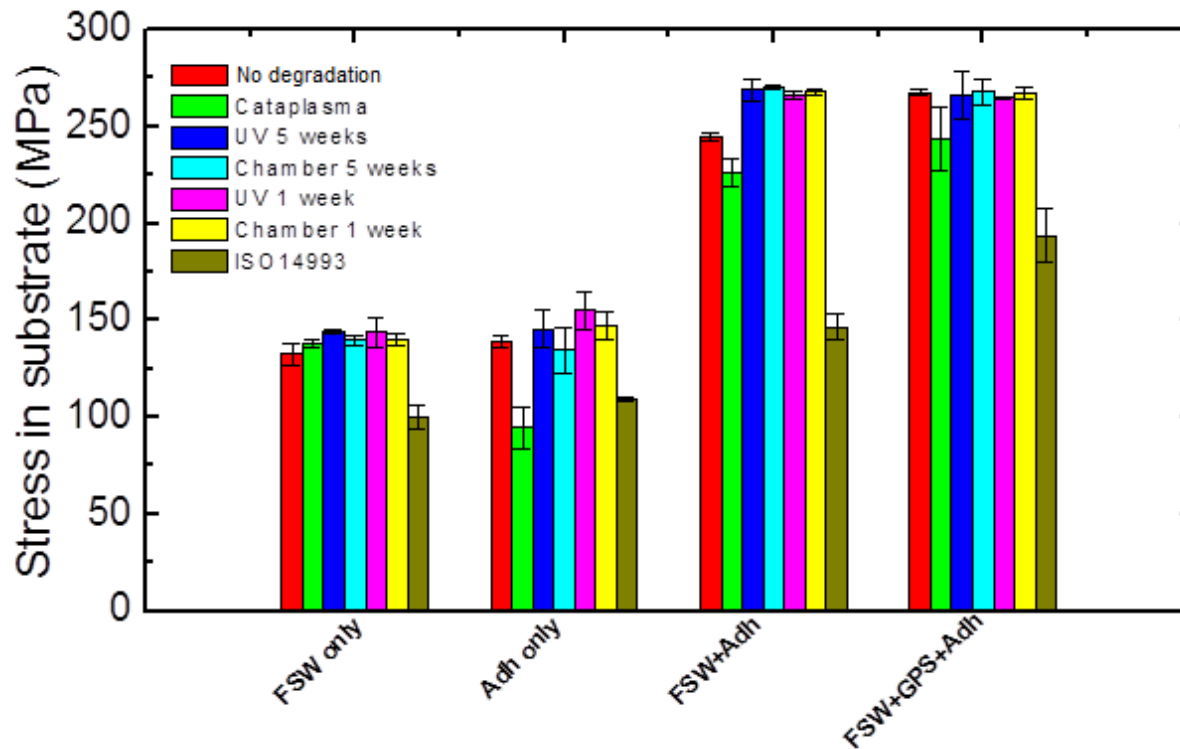
**No major gain using a silane surface treatment**

**Adhesive application on untreated surface gives unpredictable results**

# Hybrid joining: welding processes / structural adhesives

## ■ AI / AI hybrid joining

### ➤ FSW (environmental durability performance)



➤ Cataplasma degradation (Jaguar JNS 30.03.35 standard)

➤ UV (5 weeks; wet & dry) (ISO 11507: alternative exposure of 4 h UV at 60 °C and 4 h condensation (100% RH) at 50 °C for 5 weeks (35 days))

➤ Chamber 5 weeks (wet & dry conditions; replica of ISO 11507 without UV)

➤ UV (1 week, dry conditions) (ASTM D-904: 24 h UV for 7 days at 60 °C; in other words 168 h of UV exposure at 60 °C)

➤ Chamber 1 week (dry conditions; replica of ASTM D-904 without UV)

➤ Cyclic corrosion (ISO 14993)

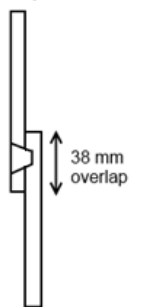
**Still + 50% joint strength in hybrid joining in environmental durability testing**

# Hybrid joining: welding processes / structural adhesives

## Al / Steel hybrid joining (FSW)

### ➤ Joint performance

Single lap-shear test



No joint strength increases using hybrid joining in conventional FSW

Tierce material	Shoulder diameter	Forge force	Joint resistance Load / weld length
	mm	kN	N / mm
Conventiounal FSW	14.0	12.0	431.2 +/- 51.8 <sup>1</sup>
Assisted FSW	11.0	5.00	234.8 +/- 5.6 <sup>1</sup>
	18.0	13.5	338.0 +/- 7.6 <sup>1</sup>
Hybrid-conventiounal FSW	14.0	12.0	415.9 +/- 38.7 <sup>1</sup>
Hybrid-assisted FSW	11.0	5.00	400.3 +/- 14.8 <sup>2</sup>

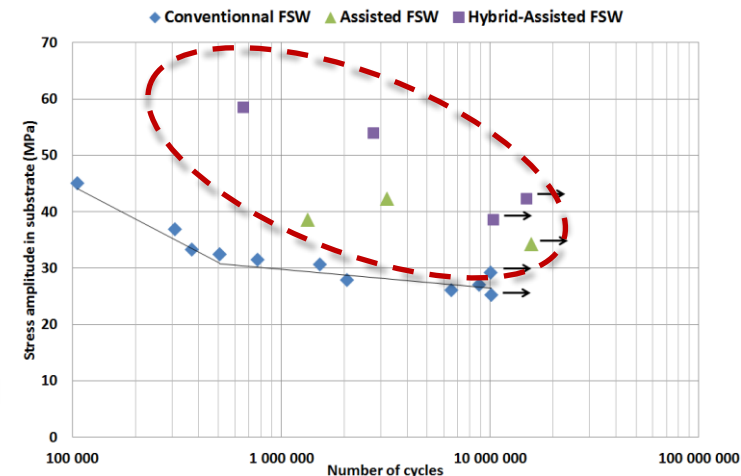
<sup>1</sup>Joint failure at interface

<sup>2</sup>Joint failure in base material (2.0mm thick)

Tierce material acts as a pre-treatment to adhesive bonding



Increase in fatigue strength vs conventiounal FSW



# FSSW: techniques & joint performance

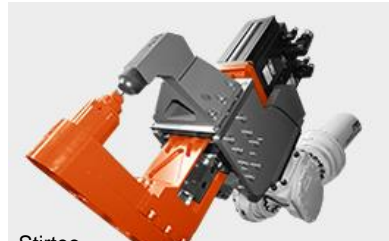
## Joining processes

### Resistance spot welding



Centerline

### Friction stir spot welding



Stirtec

### Laser welding



General Motors Co.

### Clinching



Tox pressotechnik

### Self-piercing rivets



Henrob

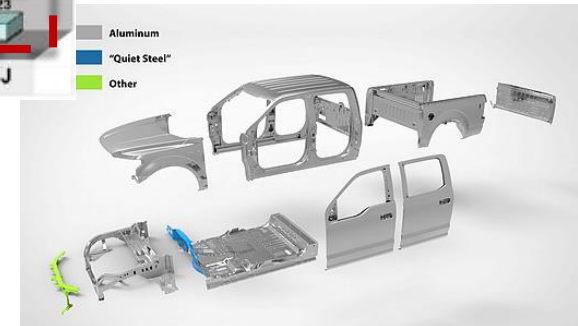
## Typical applications

### B-pillar

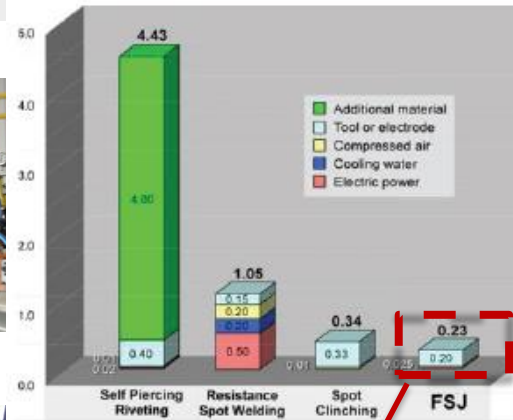


Chevrolet Corvette

### Body-in-white



Ford F-150



Typically low production cost

- Aluminum
- "Quiet Steel"
- Other

# FSSW: techniques & joint performance

## FSSW (Friction Stir Spot Welding)

### FSSW



Huys Industries



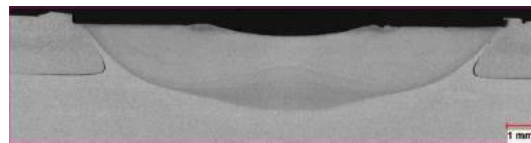
Kawasaki



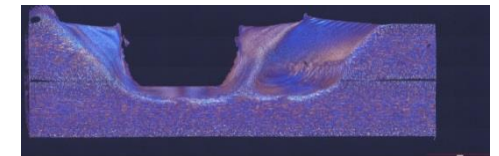
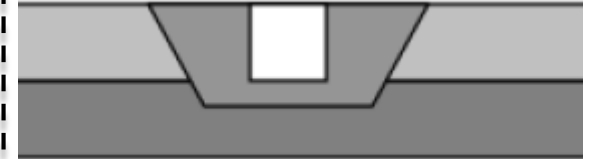
### Refill FSSW



Lower-size robot  
(C-frame)



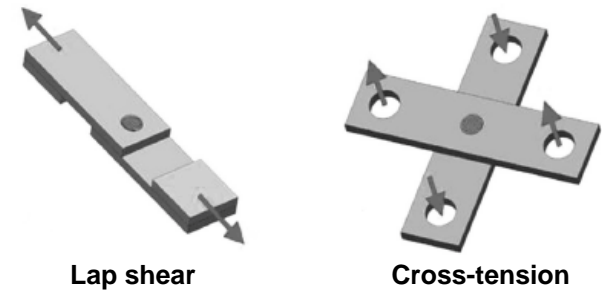
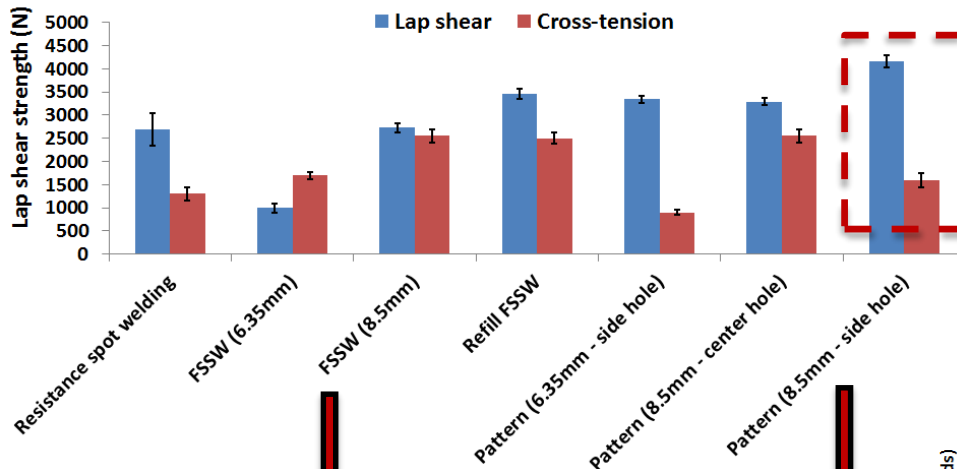
### Pattern FSSW



# FSSW: techniques & joint performance

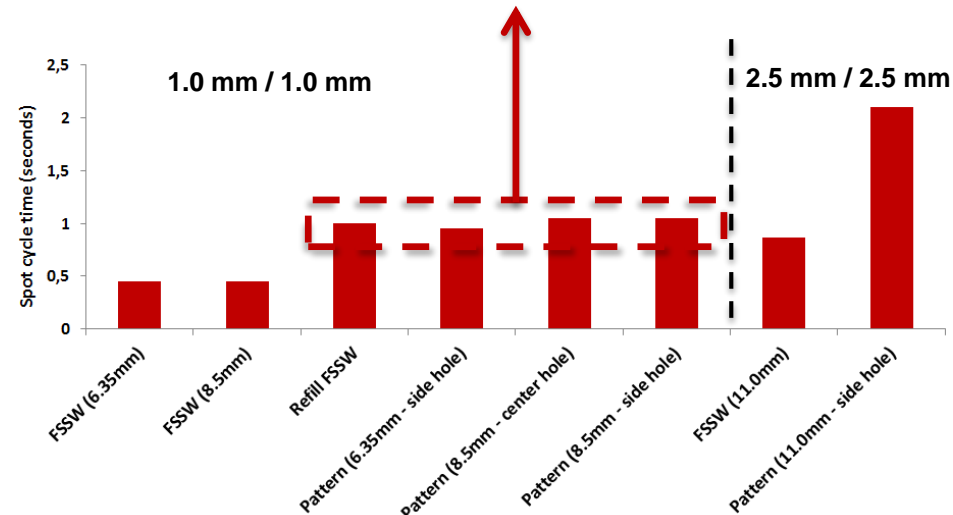
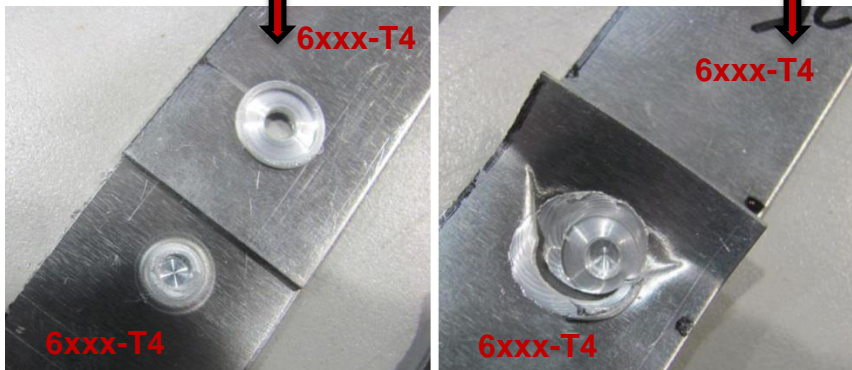
## ■ FSSW (Friction Stir Spot Welding)

### ➤ Joint performance



### Pattern FSSW

- Highest lap shear strength
- Acceptable cross-tension strength
- Same cycle time

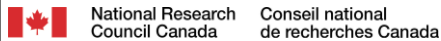




# Robotic FSW developments

- Industrialization of NRC robotic FSW technologies
  - 1<sup>st</sup> production-level robotic FSW workcell in Canada (in progress)

## Fully-integrated industrial solution



- In-house robotic FSW process (KRL,RSI) and workcell supervisory control
- In-house hybrid force control (RSI)
- Management of FSW spindle (ProfiBus)
- Process supervision module
- Recovery modes (tool auto retract)
- Human Machine Interface

## Industrial robot configuration

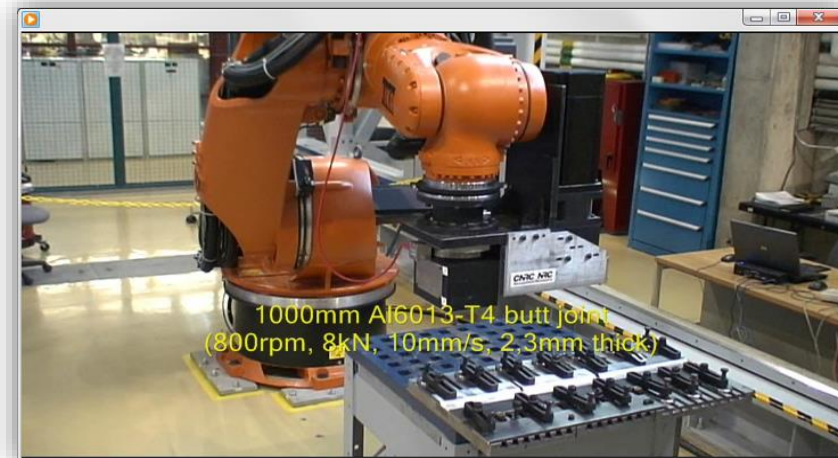


- KR500MT-2 robot arm (KRC2)
- 5 meters linear unit
- KUKA.RobotSensorInterface
- EtherNet/IP-ProfiBus

## FSW Spindle



- Spindle torque motor
- 5000 rpm / 75 Nm
- Shear force transducers
- HSK tool interface
- Hydraulic tool changing unit



## RSI-based (KRC2 12ms) real-time control features:

- Hybrid position/force control module
- Control of tool plunge + transient regime

## Accuracy management



- Automated calibration for robots working under high process loads
- Real-time corrections of tool deviations due to process loads (forge force > 8 kN)
- Real-time corrections of orientation errors

## Automated FSW fixture



- Top loading of plates
- Automated positioning of Aluminium plates (pneumatic)
- Automated horizontal & vertical clamping (hydraulic)
- Integrated cooling in backing

## FSW tools - parameters

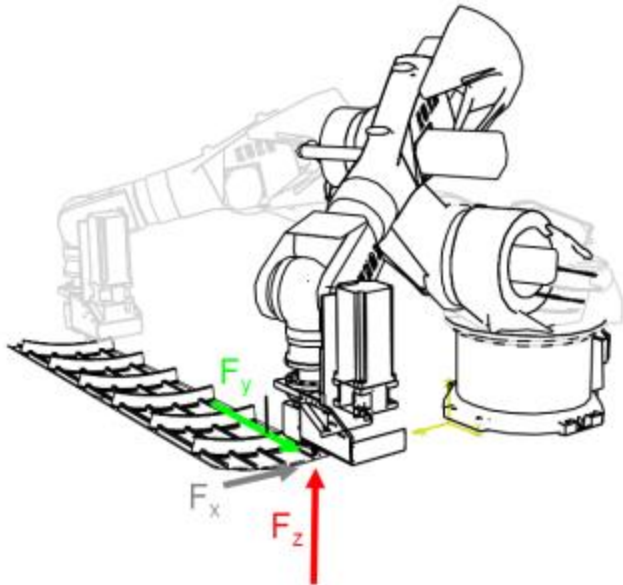


- Design of production tools (HSK)
- Specialized tool geometry with > 1000 m life (Tungsten Carbide)
- Optimized process parameters for each range of plate thicknesses (4 tools)

# Robotic FSW developments

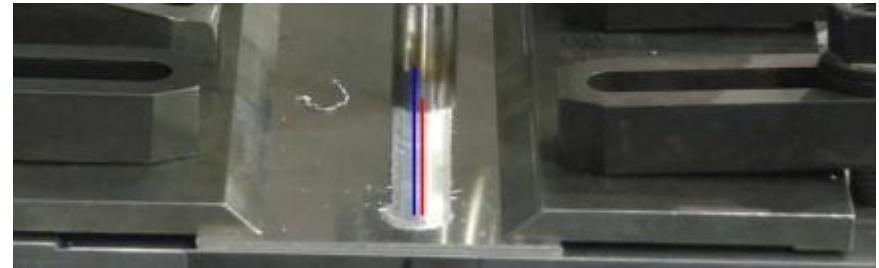
## ▪ Robotic friction stir welding: Control challenges

### Elastodynamic behavior of serial robots



- FSW tool deviations (axial + transverse joint deformations, backlash, ...)
- Automation problem at tool plunge-in
- Vibrations due to robot dynamics (rpm < 1000)

### Robotization issues & seam defects



Al 2024-T3 (2x2,3mm) Lap joint, 750rpm (robot natural frequency)



robot oscillations during weld

# Robotic FSW developments

- Technology package for accurate path generation using rail-mounted robots under load (TRL-8)

## NRC calibration kit & method

- > Model for axial+structural behavior
- > Solution for *improved measurement of lateral forces for COTS spindles*
- > Fully automated robot calibration in production-relevant envelope (*PCT patent pending*)
- > Fully automated parameter estimation



accuracy performance

## NRC 3D real-time path correction technology

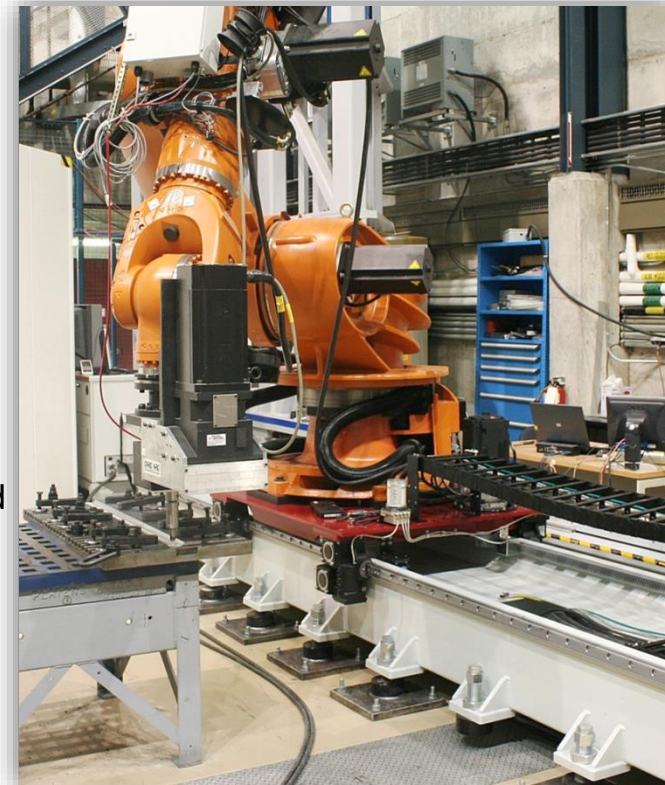
- > Real-time compensation of deviations in welding plane
- > Compensation of force-induced loss of angularity

### Initial situation:

Lateral deviations in seam plane + loss of angularity caused by heavy process loads

## Standard kinematic calibration

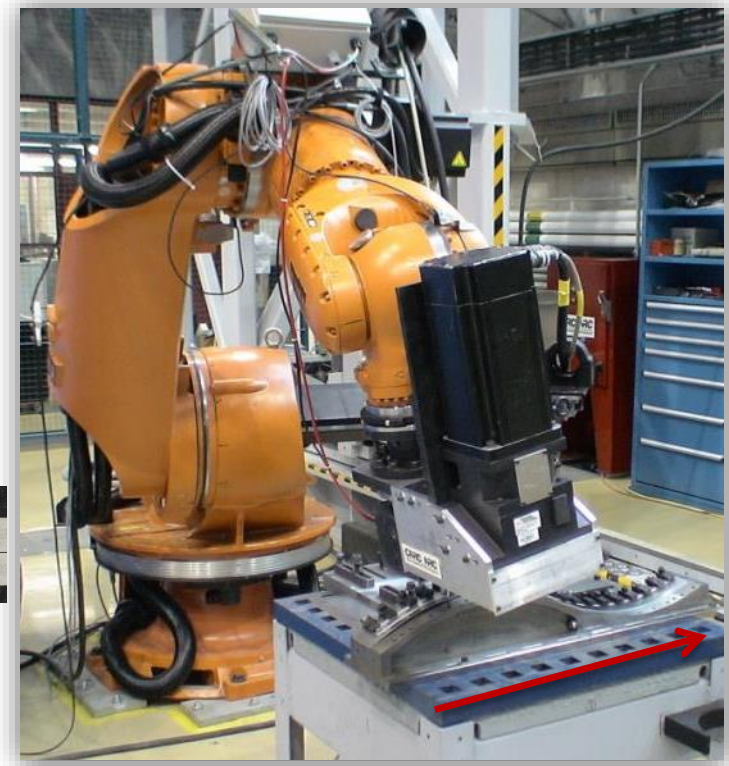
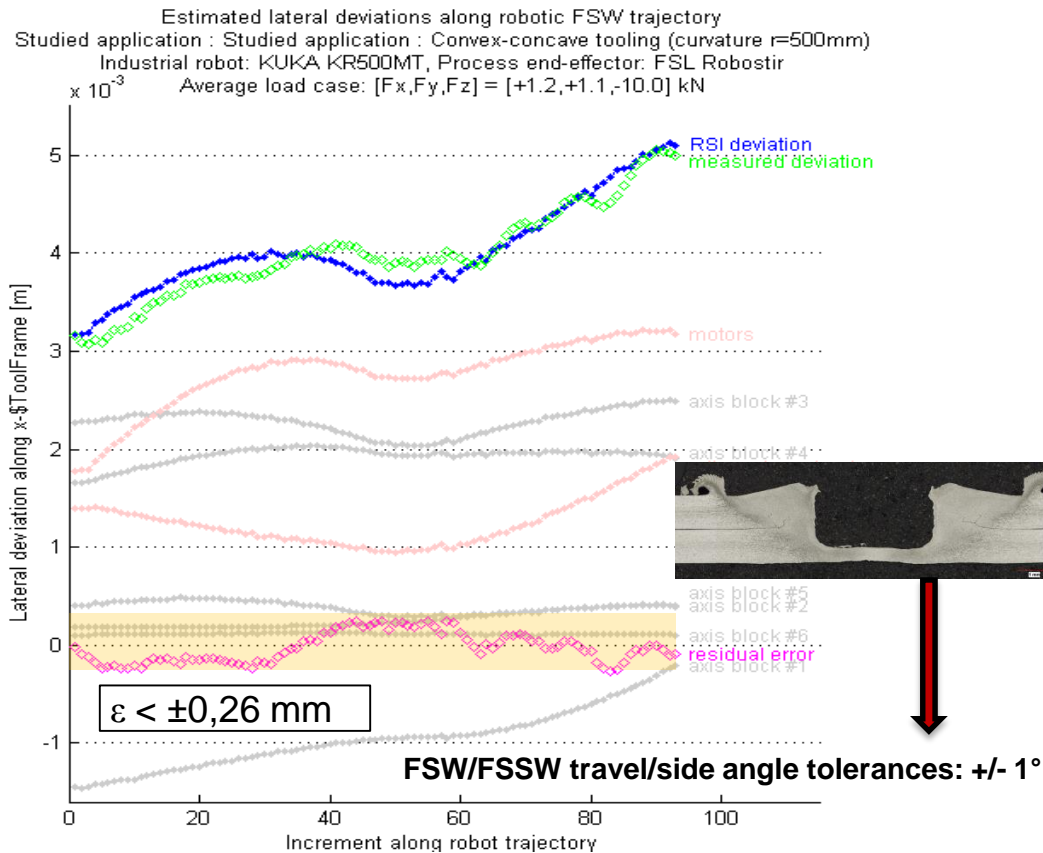
- > Calibration of robot path generation errors in free motion (e.g.: KUKA Absolute Accuracy)
- > Local robot/tooling calibration



# Robotic FSW developments

- Performance evaluation on NRC robotic FSW test-bed

Real-time compensation of lateral/angular deviations along 3D convex-concave profile — Forward path

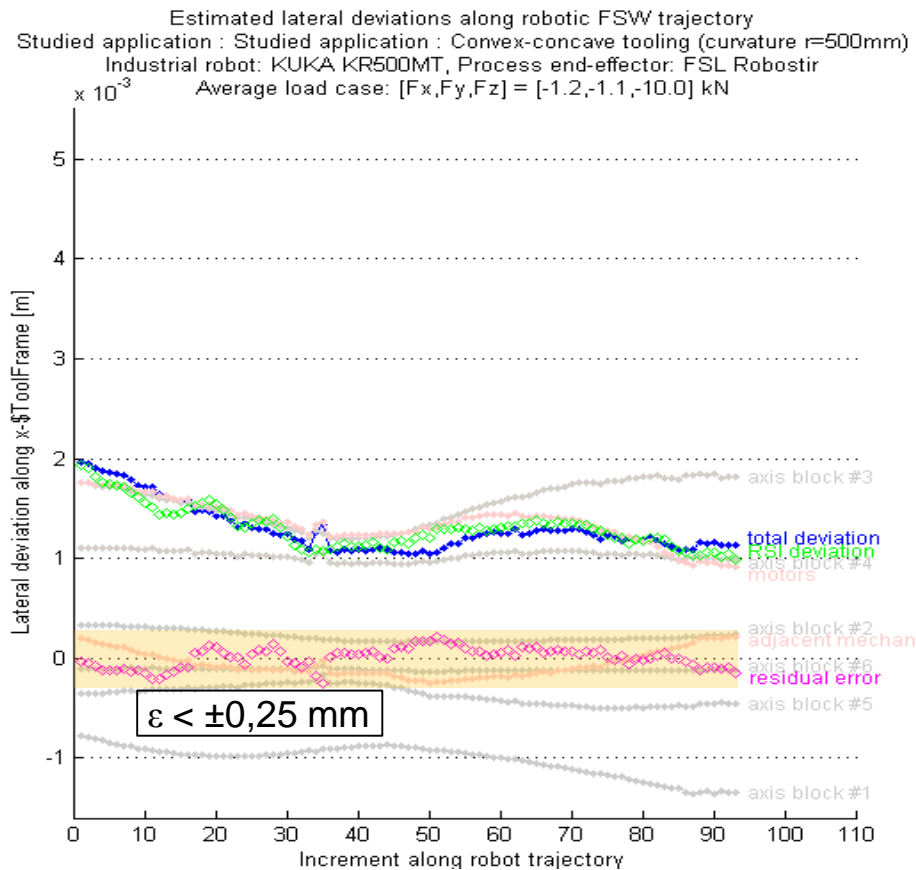


Process forces:  $F_x = 1,2$  kN,  $F_y = 1,1$  kN,  $F_z = 10$  kN  
 Hybrid position/force control

# Robotic FSW developments

- Performance evaluation on NRC robotic FSW test-bed

Real-time compensation of lateral/angular deviations along 3D convex-concave profile — Return path



Process forces:  $F_x = 1,2 \text{ kN}$ ,  $F_y = 1,1 \text{ kN}$ ,  $F_z = 10 \text{ kN}$   
 Hybrid position/force control

# Questions ?

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